

CS 331, Fall 2025

Lecture 26 (12/8)

Today: - Kevin's research

- Fine-grained complexity

- Popular conjectures

Kevin's research

Algorithmic primitives for "big" data science

$\approx 1/2$: continuous algos foundations (opt, samp, NLA)

$\approx 1/2$: trustworthy ML (robustness, privacy, fairness)

Key themes:

- Many problems hard in worst case. Harness structure.
- Where does the data come from? Minimal assumptions.
- Dataset sizes enormous, only growing. Nex-linear time?

Trustworthy ML

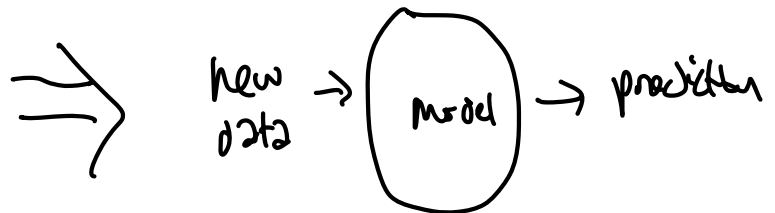
Textbook setting for statistics / learning:

$$\begin{matrix} X_1 = (&) \\ X_2 = (&) \\ X_3 = (&) \\ & \vdots \\ X_n = (&) \end{matrix} \sim \text{known density, e.g. Gaussian}$$

$$\Rightarrow A(\text{data})$$

analyst runs
learning algo
to train model

Real life is harder.



- What if we're wrong about the data? Robustness
- The data is coming from humans. Privacy / fairness
- Why do we believe the model's conclusion? Interpretability
- ... all needs to happen efficiently ...

Continuous algos

What kind of tools are useful for modern algo design?

OPT: Minimize structured objectives.

e.g. minimax / stochastic optimization

Semidefinite programming ("matrix LP")

Structured nonconvex problems (Sparsity, GLM, ...)

SAMP: Sample from structured densities.

e.g. logconcave sampling (basic tractable family)

Structured multimodal problems

NLA: numerical linear algebra primitives

e.g. preconditioning (solving linear systems, regression)

Sparsification (reduce data w/ representatives)

2014: Google internship. Not good at it...

2015: Complexity research. Not good at it...

2016: Genomics research. Really fun! I liked algos best...

2017: Genomics / NLP / stats research. (Ph.D. rotations)

2018: Approximate maxflow.

2019: Nash equilibria, optimal transport, SDP.

2020: Sampling. SOTA for some logconcave families.

2021: Robust stats. PCA, regression, clustering in new literature.

2022-25: Privacy, interpretability, fairness, etc.

I am trying to learn more about modern ML...

Algorithms are cool and come in many
flavors. There are so many connections.

Just keep learning and enjoy ☺

More TCS @ UT!

CS 353: Theory of Computation

(a second course in complexity)

Graduate algos courses

CS 388E: Approximation

CS 388P: Randomized

CS 389C: Continuous

CS 390S: Sublinear

Graduate complexity courses

CS 388T: Complexity theory

CS 388M: Communication

What else?

CS 346/388H: Cryptography

CS 358H/378H: Quantum information

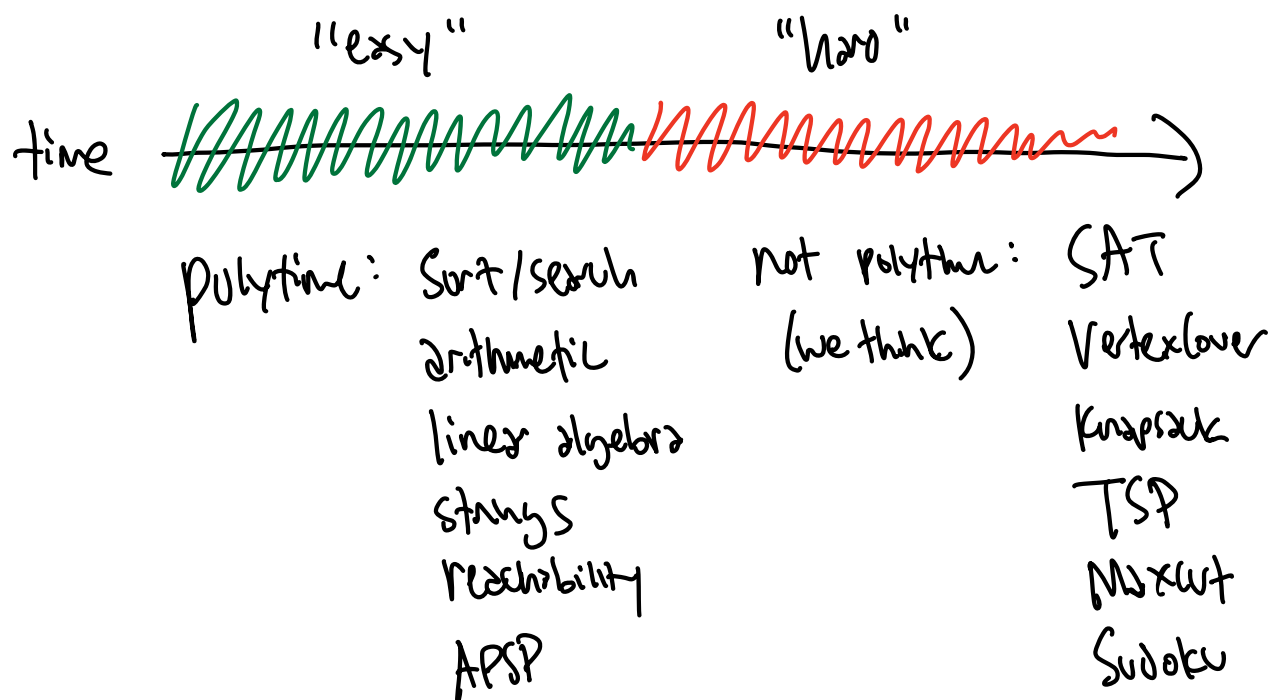
... many more rotating
topics classes

Fine-grained complexity

Thanks to: Virginia Williams (notes)
Amir Abboud } [Youtube](#)
Nick Fischer }

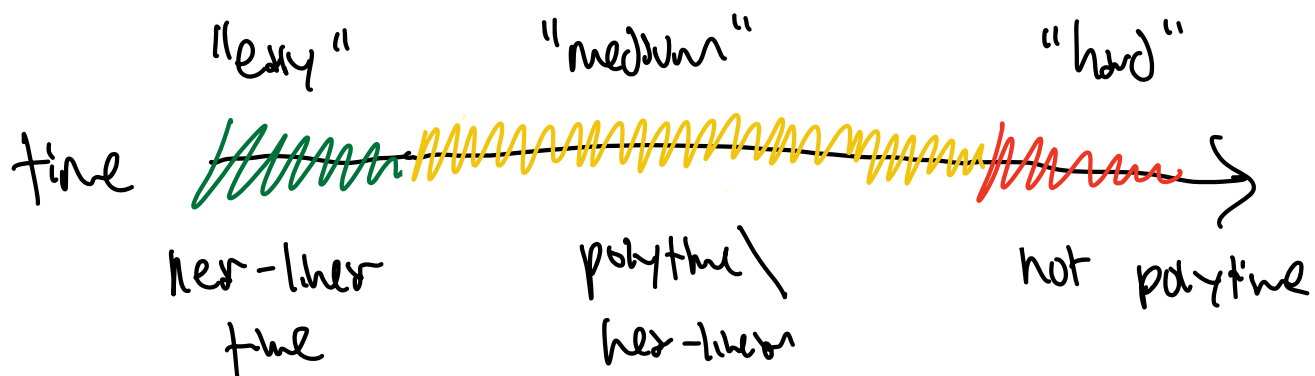
So far: Complexity theory for "small data"

$$n = 100, 1000, 10000 \dots$$



It's 2025. We need complexity theory for "big data"

$$n = 10^9, 10^{12}, 10^{15} \dots$$



NP: a tool to prove problems **hard**.

Today: how to prove problems **medium**.

Known **easy**

FFT

Shortest path

Maxflow

Longest increasing subseq.

Closest pair in \mathbb{R}^2

Longest palindromic substring

Suspected **medium**

3-SUM

All pairs shortest paths

Dynamic maxflow

Longest common subseq.

Closest pair in \mathbb{R}^d

Edit distance

e.g. APSP

n^3

...

...

$n^{3-o(1)}$

Floyd-Warshall '62

Williams '14

Why are we so good at problems on LHS
... but bad at problems on RHS?

Goal in FGC: web of reductions, common source of hardness
must attack first!

Popular Conjectures

Let $\epsilon > 0$ be small constant.

3-SUM: Given list L of #'s, \exists $a, b, c \in L$
s.t. $a + b + c = 0$?

... cannot be solved in time $O(|L|^{2-\epsilon})$

APSP: Given graph $G = (V, E, w)$ compute
 $|V| \times |V|$ matrix encoding all-pairs shortest paths
... cannot be solved in time $O(|V|^{3-\epsilon})$

SETH: \exists constant k s.t. k -SAT on

Φ w/ m clauses, n variables

... cannot be solved in time $O(2^{n^{1-\epsilon}} \text{poly}(n))$

Rough intuition: we care about the exponent now.

3-SUM

Computational geometers Gajentaan - Overmars '95

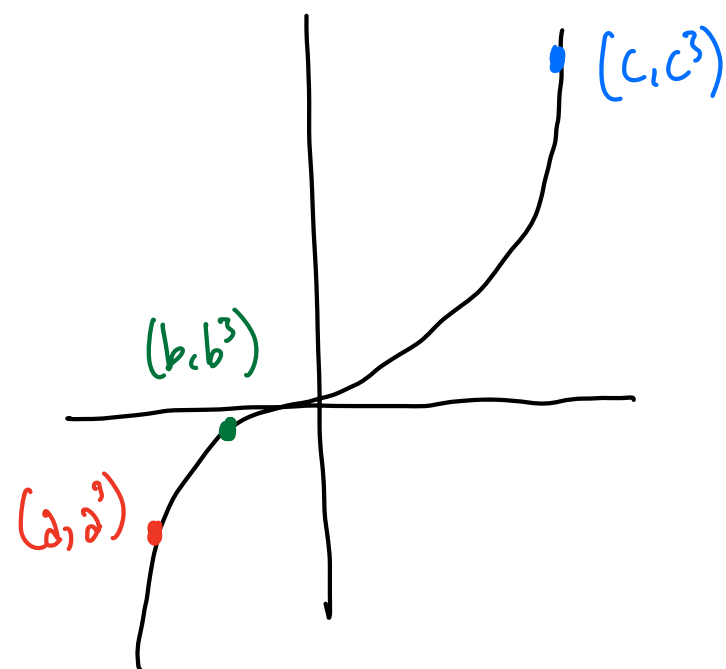
kick off field of FGC by reducing to 3-SUM.

Example: collinearity requires $\approx n^2$ time.

Input: n points in \mathbb{R}^2 . \exists three on a line?

(This proof is crazy.) Reduce 3-SUM to collinearity.

Check collinearity $(\{(x, x^3) \mid x \in L\})$



$$\frac{b^3 - a^3}{b - a} = \frac{c^3 - b^3}{c - b}$$

$$a^2 + ab + b^2 = c^2 + cb + b^2$$

$$a^2 - c^2 = b(c - a)$$

$$-a - c = b \quad (3\text{-SUM})$$

More: visibility / reachability
 motion planning
 polygon containment

} Several require ingenuity to solve in $\approx n^2$.

APSP

This is really about "Combinatorial" matrix multiplication.

Many amazing "algebraic" innovations:

$(n \times n) (n \times n)$ takes time...
 ↑ ↑
 multiply

n^3 (duh)
 $n^{2.807}$ Strassen
 \vdots
 $n^{2.3714}$ ADWXXZ

Use crazy cancellations on huge tensors...

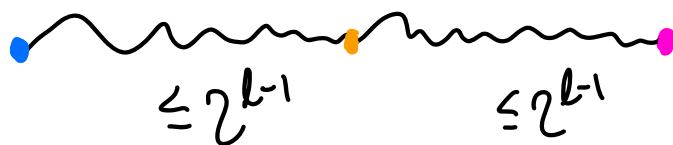
What if we can only use more "baseline" techniques?

Recall divide-and-conquer + DP also for APSP

$DP[s][t][\ell]$: shortest $s-t$ path w/ $\leq 2^\ell$ edges

$$= \min_{u \in V} DP[s][u][\ell-1] + DP[u][t][\ell-1]$$

"guess the midpoint"



This is the same problem as "dot product"

except Sum \rightarrow min
 product \rightarrow sum

$$DP_{l-1} \otimes DP_{l-1} = DP_l \quad \forall l \in [O(\log(n))]$$

↑
"min-plus" convolution

To solve APSP, need to solve combinatorial matrix $O(\log(n))$ times. Thus, APSP conjecture:

Combinatorial matrix needs $\approx n^3$ time $\ddot{\smile}$

Good news: structured matrix / inversion / ... easier!

SETH

Recall 3-SAT solvable in: $O(2^n n)$ time

Improvement: Try 7/8 for one clause, recurse.

$$T(n) \leq 7T(n-3) + O(n) \Rightarrow T(n) = O(1.913^n n)$$

So, 3-SAT does not need 2^n time.

More general: k -SAT in $2^{n(1-o(1))}$ in time.

But we need tight base (will later choose $n = \log$)
base becomes exponent.

Hence SETH: Choose large enough k .

Almost all modern reductions use SETH thru:

$$\text{SETH} \leq \text{OV}$$

(orthogonal vectors)

Williams, 2005

OV implies FGL of so many problems:

- Diameter
- Edit distance
- Local diameter
- Dynamic reachability
- Fréchet distance
- Stable matching
- Single-source max flow
- LCS
- Closest pair

2-OV problem:

let $d = \omega(\log n)$ "sparse subset"

$A, B \subset \{0,1\}^d$, size n

$\exists a \in A, b \in B$ s.t. $\underbrace{a^T b}_{\text{orthogonal vectors}} = 0?$

Conjecture: no better than $\approx n^2 d$ possible.

k-OV: there are k sets

$A_1, A_2, A_3, \dots \subset \{0,1\}^d$

$\exists a_1 \in A_1, a_2 \in A_2, a_3 \in A_3, \dots$

s.t. $\sum_{i \in [d]} a_1[i] a_2[i] a_3[i] \dots = 0?$

Conj: needs $\approx n^k d$ time.

Obs 1: 2-OV is very fundamental. FGC!

Obs 2: $2\text{-OV} \geq 3\text{-OV} \geq \dots \geq k\text{-OV}$.

Obs 3: "OV \geq SETH".

Suppose there's $k\text{-OV}$ in $O(N^{k(1-\epsilon)})$.

Take $k\text{-SAT}$ formula Φ , n variables
in clauses

Create $A_1, \dots, A_k \subset \{0,1\}^n$:

$$x \in \{0,1\}^n \rightarrow \left(\underset{n/k}{x_1} \mid \underset{n/k}{x_2} \mid \dots \mid \underset{n/k}{x_k} \right)$$

blocks

A_i = index by $N = 2^{n/k}$ assignments to i^{th} block

Faster \Rightarrow SAT in time $N^{k(1-\epsilon)} = 2^{n(1-\epsilon)}$
 $k\text{-OV}$ (violates SETH!)